## **CLAIMS**

## What is claimed is:

1	1.	A system for detecting a downhole condition in a wellbore during a non-drilling wellbore		
2	operation, the system comprising:			
3		a tool string to be disposed within a wellbore;		
4		a workpiece within the tool string for performing a non-drilling wellbore operation within the		
5	wellbore; and			
6		a condition sensing tool within the tool string for sensing a downhole condition.		
1	2.	The system of claim 1 wherein the workpiece comprises a fishing device.		
1	3.	The system of claim 1 wherein the workpiece comprises a cutting tool.		
1	4.	The system of claim 3 wherein the cutting tool comprises an underreamer.		
1	5.	The system of claim 3 wherein the cutting tool comprises a casing cutter.		
1	6.	The system of claim 1 wherein the downhole condition is a condition from the set consisting		
2	essentially of torque, weight, tool string compression, tool string tension, speed of tool string			
3	rotation, vibration, and direction of tool string rotation.			
1	7.	The system of claim 1 wherein the condition sensing tool of the system comprises:		
1	1.	an outer housing defining a sensor section therein; and		
2				
3		at least one sensor retained within the sensor section for detection of a downhole condition.		

- 1 8. The system of claim 7 wherein the condition sensing tool further comprises a processing
- 2 section for receiving data relating to the downhole condition and transmitting the data to a remote
- 3 receiver.
- 1 9. The system of claim 7 wherein the condition sensing tool further comprises a processing
- 2 section for receiving data relating to the downhole condition and storing the data.
- 1 10. The system of claim 1 further comprising a power section.
- 1 11. A condition sensing tool for use within a wellbore during a non-drilling operation to detect at
- 2 least one downhole condition within the wellbore, the condition sensing tool comprising:
- an outer housing defining an axial fluid flowbore therethrough;
- a sensor section defined within the housing; and
- at least one sensor for detecting at least one non-drilling downhole condition from the set of
- 6 conditions consisting essentially of torque, weight, tool string compression, tool string tension, speed
- of tool string rotation, vibration, and direction of tool string rotation.
- 1 12. The condition sensing tool of claim 11 further comprising a power section within the housing
- 2 for supplying power to the sensor section.
- 1 13. The condition sensing tool of claim 11 further comprising a processing section for receiving
- 2 data relating to the downhole condition and transmitting the data to a remote receiver.
- 1 14. A method of performing a non-drilling downhole wellbore operation comprising:
- 2 integrating a workpiece and a condition sensing tool into a tool string;
- disposing the tool string into a wellbore;

actuating the workpiece to conduct a non-drilling downhole operation; and 4 detecting at least one downhole condition with the condition sensing tool. 5 The method of claim 14 further comprising the step of transmitting information indicative of 15. 1 the downhole condition to a remote location. 2 The method of claim 14 further comprising the step of storing information indicative of the 16. 1 downhole condition within a processing section of the condition sensing tool. 2 The method of claim 14 wherein 17. 1 the workpiece comprises a fishing tool for engaging a stuck member within a a) 2 wellbore; 3 the non-drilling downhole operation comprises a fishing operation to remove a stuck **b**) 4 member from the wellbore; and 5 the condition sensing tool detects weight and torque. c) 6 The method of claim 14 wherein: 18. 1 the workpiece comprises an anchor latch; 2 a) the non-drilling downhole operation comprises unthreading of a threaded connection 3 b) within the wellbore; and the condition sensing tool detects tool string compression and tool string tension. c) 5 The method of claim 14 wherein: 19. 1 the workpiece comprises a casing cutter; a) 2 the non-drilling downhole operation comprises a casing cutting operation, and b) 3 the condition sensing tool detects speed and direction of rotation of the tool string. 4 c)

1	20.	The method of claim 14 wherein:		
2		a)	the workpiece comprises an underreamer;	
3		b)	the non-drilling downhole operation comprises an underreaming operation, and	
4		c)	the condition-sensing tool detects torque.	
1	21.	The method of claim 20 wherein the condition sensing tool also detects weight, speed of		
2	rotatio	on, and direction of rotation.		
			,	
1	22.	The method of claim 14 wherein:		
2		a)	the workpiece comprises a packer;	
3		b)	the non-drilling downhole operation comprises retrieval of the packer from a set	
4			position within the wellbore; and	
5		c)	the condition-sensing tool detects torque and weight.	
1	23.	The method of claim 14 wherein:		
2		a)	the workpiece comprises a pilot mill;	
3		b)	the non-drilling downhole operation comprises milling away by the pilot mill of a	
4			portion of a tubular member within the wellbore; and	
5		c)	the condition sensing tool detects at least some of the downhole conditions from the	
6			set of conditions consisting essentially of torque, direction of rotation, speed of	
7			rotation, weight, tool string compression, and tool string tension.	
1	24.	The method of claim 14 wherein:		
2		a)	the workpiece comprises a washover tool;	
3		b)	the non-drilling downhole operation comprises a washover operation for cutting away	
4			portions of a formation surrounding a stuck object within the wellbore; and	

21

284-34922-US

- 5 c) the condition sensing tool detects torque.
- 1 25. The method of claim 24 wherein the condition sensing tool further detects speed and
- 2 direction of rotation.